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### Ground State Solutions for A Quasilinear Elliptic Problem with a Convection Term

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## Abstract

By a sub-supersolution argument and a perturbed argument, we improve the earlier results concerning the existence of ground state solutions to a quasilinear elliptic problem

 $-\operatorname{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), u > l \ge 0, x \in \mathbb{R}^N, \lim_{|x| \to \infty} u(x) = l,$ 

where  $p \ge 2, q > p-1, p(x) \in C^{\alpha}_{loc}(\mathbb{R}^N)$  for some  $\alpha \in (0, 1)$  is non-negative and  $f : \mathbb{R}^N \times (0, \infty) \rightarrow [0, \infty)$  is a locally Hölder continuous function which may be singular at zero.

*Keywords: existenceground solution, quasilinear elliptic, convection term.* 2010 Mathematics Subject Classification: 35J65; 35J50.

# 1 Introduction and The Main Results

In this paper, we are concerned with the existence of ground state solutions for the following problem

$$-\mathrm{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), u > l \ge 0, x \in \mathbb{R}^N, \lim_{|x| \to \infty} u(x) = l,$$

We first consider l = 0, then the problem becomes as follows

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), \\ u > 0, x \in \mathbb{R}^N, \\ \lim_{|x| \to \infty} u(x) = 0, \end{cases}$$
(1)

where  $p \ge 2, q > p - 1, p(x) \in C^{\alpha}_{loc}(\mathbb{R}^N)$  for some  $\alpha \in (0, 1)$  is non-negative and  $f : \mathbb{R}^N \times (0, \infty) \to [0, \infty)$  is a locally Hölder continuous function which may be singular at zero.

In recent years, the study of ground state solutions, that is, positive solutions defined in the whole space  $\mathbb{R}^N$  and decaying to zero at infinity, has received a lot of interest and numerous existence

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results have been established. Concerning ground state solutions for elliptic problems with a convection term, we refer readers to (Xue and Shao, 2009; Xue, 2011; Dinu, 2003; Goncalves and Silva, 2010), and the reference therein. Meanwhile , we also see that most of these investigations focus on the following problem

$$\begin{cases} -\Delta u + p(x) |\nabla u|^q = b(x)g(u), \\ u > 0, x \in \mathbb{R}^N, \\ \lim_{|x| \to \infty} u(x) = 0, \end{cases}$$
(2)

Throughout the papers, authors assume that  $g \in C^1((0,\infty),(0,\infty))$ , additionally, with regard to g, consider the hypothesis

- (g1) g is increasing on  $(0, \infty)$ ;
- (g2)  $\lim_{s \to 0^+} g(s) = \infty;$
- (g3) q is bounded in a neighborhood of  $\infty$ ;
- (g4)  $\lim_{s \to 0^+} \frac{g(s)}{s^{p-1}} = \infty;$
- (g5)  $\frac{g(s)}{(s+c_0)^{p-1}}$  is decreasing on  $(0,\infty);$
- (g6)  $\frac{g(s)}{s^{p-1}}$  is decreasing on  $(0,\infty)$ ;

(g7)lim<sub>s 
$$\rightarrow \infty$$</sub>  $\frac{g(s)}{s^{p-1}} = 0;$ 

And b(x) satisfies

(b1)  $b: \mathbb{R}^N \to (0, \infty)$  is a locally Hölder continuous function, (b2) the problem

$$\begin{cases}
-\operatorname{div}(|\nabla u|^{p-2}\nabla u) = b(x), \\
u > 0, x \in \mathbb{R}^{N}, \\
\lim_{|x| \to \infty} u(x) = 0,
\end{cases}$$
(3)

has a solution  $w \in C^{1+\alpha}_{loc}(\mathbb{R}^N)$ . (Dinu, 2003) showed that problem (2) has a unique solution in the case when  $g(u) = u^{-\gamma}$  with  $\gamma > 0$ . Later the paper (Xue and Shao, 2009) has showed problem (2) has at least one solution if gsatisfies (g4) and (g7) and b satisfies (b1) and (b2).

For corresponding quasilinear elliptic equations, more specifically, when p(x) = 0, in (Yang and Yu, 2010) studied the following model

$$\begin{pmatrix}
-\operatorname{div}(|\nabla u|^{p-2}\nabla u) = \rho(x)f(u), \\
u > l, x \in \mathbb{R}^{N}, \\
\lim_{|x| \to \infty} u(x) = l,
\end{cases}$$
(4)

where N> 3 and l>0 is a real number. (Yuan and Yang, 2010) has showed the existence and asymptotic behavior of radially symmetric ground states of (4). (Liu and Yang, 2010) studied

$$\begin{cases} -\operatorname{div}(|\nabla u|^{m-2}\nabla u) - |\nabla u|^{q(m-1)} = b(x)g(u), \\ u > 0, x \in \Omega, \\ u|_{\partial\Omega} = +\infty, \end{cases}$$
(5)

where  $\Omega$  is a  $C^2$  bounded domain with smooth boundary,  $m > 1, q \in (1, \frac{m}{m-1}]$ . (Liu and Yang, 2010) has showed the existence of large solutions of (5).

But the results about the existence of ground state solutions for a quasilinear elliptic problem with a convection term are few. For the following problem

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p-2}\nabla u) + h(x)|\nabla u|^q = b(x)g(u), \\ u > 0, x \in \mathbb{R}^N, \\ \lim_{|x| \to \infty} u(x) = 0, \end{cases}$$
(6)

(Shen and Zhang, 2011) has showed that (6) has at least one solution if g satisfies (g4) and (g7), and b satisfies (b1) and (b2).

The purpose of this paper is to investigate the existence of ground state solutions for problem (1), which includes problem (6) as a particular case. And we modify the method developed in (Xue, 2011) and extends the results obtained in (Xue, 2011; Shen and Zhang, 2011).

In this paper, we suppose that

(f1) f(x,s) is locally Hölder continuous on  $\mathbb{R}^N \times (0,\infty)$  and continuously differentiable in the variable s;

(f2)  $f(x,s) \le b(x)g(s)$  for all  $(x,s) \in \mathbb{R}^N \times (0,\infty)$ , where b satisfies (b1), (b2), g satisfies

 $(g8) \lim_{s \to \infty} \sup \frac{g(s)}{s^{p-1}} < ||w||_{\infty}^{1-p}$ , where w is the solution of problem (1.3) and  $||w||_{\infty} := \max_{x \in \mathbb{R}^N w(x)}$ ; (f3) There exists  $s_0 > 0$  such that  $f(x, s) \ge a(x)n(s)$  for all  $(x, s) \in \mathbb{R}^N \times (0, s_0)$ , where  $a : \mathbb{R}^N \to (0, \infty)$  is locally Hölder continuous and n satisfies

 $(n1)n: (0, s_0) \rightarrow (0, \infty)$  is continuous.

Our main result is summarized in the following theorem.

**Theorem 1.** Let q > p - 1,  $p(x) \in C_{loc}^{\alpha}(\mathbb{R}^N)$  be non-negative. If f satisfies (f1) - (f3), g satisfies (g8), n satisfies (n1) and  $(n2) \lim_{s \to 0^+} \frac{n(s)}{s^{p-1}} = \infty$ , then problem (1.1) has at least one solution  $u \in C^{1+\alpha}(\mathbb{R}^N)$ .

The paper is organized as follows. In Section 2, we provide a suitable supersolution for problem (1) and show the existence of positive solutions in bounded domain. In Section 3, we prove Theorem 1, moreover, we will study the case l > 0.

#### 2 Preliminary

The result below will provide a suitable supersolution for problem (1).

**Lemma 2.1.** If *b* satisfy (*b*1) and (*b*2), and *g* satisfies (*g*8), then there exists a function  $v := \Psi(\gamma w(x)) \in C^1_{loc}(\mathbb{R}^N)$  such that

$$-\operatorname{div}(|\nabla v|^{p-2}\nabla v) \ge b(x)g(v(x)), \quad v(x) > 0, x \in \mathbb{R}^N, \lim_{|x| \to \infty} v(x) = 0,$$
(7)

for large  $\gamma \geq 1$ , where w is the solution of problem (3).

**Proof.** Since g satisfies (g8), we define

$$\widehat{g}(t) := \sup\{\frac{g(s)}{s^{p-1}} : s > t\}, \qquad t > 0.$$
(8)

we denote that  $\widehat{g}$  is non-increasing, positive and  $\widehat{g}(t) \geq \frac{g(t)}{t^{p-1}}$ . Furthermore, by (g8) we have  $\widehat{g}(t) < |w|_{\infty}^{1-p}$  for sufficiently large t. Let

$$h(t) := \frac{2}{t} \int_{\frac{t}{2}}^{t} \widehat{g}(s) ds, \qquad t > 0,$$
(9)

It is shown in (Ladyzenskaja and Ural'tseva, 1968) that h is  $C^1$ , non-increasing and  $\widehat{g}(t) \le h(t) \le \widehat{g}(\frac{t}{2})$  for all  $t \in (0, \infty)$ .

Since h is non-increasing, we note that  $h(t) \to \alpha < |w|_{\infty}^{1-p}$  at  $t \to \infty$  for some  $\alpha \in [0, \infty)$ . Now let us set

$$\eta(t) := \int_0^t \frac{1}{h^{\frac{1}{p-1}}(s)} ds, \qquad t > 0,$$
(10)

On using  $\widehat{g}(t) < |w|_{\infty}^{1-p}$  in (9) for sufficiently large t > 0, we see from (10) that

$$\eta(\gamma) > \gamma |w|_{\infty}.\tag{11}$$

for a sufficiently large  $\gamma \geq 1$ .

Let  $\Psi=\eta^{-1}$  be the inverse function of  $\eta$  , i.e,  $\Psi$  satisfies

$$\int_{0}^{\Psi(t)} \frac{1}{h^{\frac{1}{p-1}}(s)} ds = t, \qquad t \in [0,\infty),$$
(12)

By direct calculation ,we see that

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$$\Psi^{'}(t) = h^{\frac{1}{p-1}}(\Psi(t)) > 0, \Psi(t) > 0, \text{ for } t > 0 \text{ and } \Psi(0) = 0.$$

By condition (b2), we take a solution w of (3) with  $\Omega = \mathbb{R}^N$ . Let us set  $v(x) := \Psi(\gamma w(x))$  for all  $x \in \Omega$ , we note from (11) that

$$v(x) = \Psi(\gamma w(x)) \le \Psi(\gamma |w|_{\infty}) < \gamma, \tag{13}$$

A simple computation shows that v has the desired properties. Indeed , on recalling  $-{\rm div}(|\nabla w|^{p-2}\nabla w)=b(x),$  we see that

$$\begin{aligned} -\mathsf{div}(|\nabla v|^{p-2}\nabla v) &= -\mathsf{div}(|h^{\frac{1}{p-1}}(v)\gamma\nabla w|^{p-2} \cdot h^{\frac{1}{p-1}}(v)\gamma\nabla w) \\ &= -\mathsf{div}(h(v) \cdot \gamma^{p-1} \cdot |\nabla w|^{p-2}\nabla w) \\ &= -\gamma^{p-1} \cdot h(v)\mathsf{div}(|\nabla w|^{p-2}\nabla w) - |\nabla w|^{p-2}\nabla w \cdot \gamma^{p-1}h^{'}(v)\Psi^{'}(\gamma w(x)) \cdot \gamma\nabla w \\ &= -\gamma^{p-1} \cdot h(v)\mathsf{div}(|\nabla w|^{p-2}\nabla w) - \gamma^{p}|\nabla w|^{p}h^{'}(v)h^{\frac{1}{p-1}}(\Psi(\gamma w(x))) \\ &\geq -\gamma^{p-1} \cdot h(v)\mathsf{div}(|\nabla w|^{p-2}\nabla w) \\ &= b(x)\gamma^{p-1}h(v) \\ &\geq v^{p-1}b(x)\frac{g(v)}{v^{p-1}} \\ &= b(x)g(v) \quad x \in \mathbb{R}^{N}, \end{aligned}$$

We have used (13) in the last inequality. Since  $\Psi(0) = 0$ , it is clear that  $v(x) \longrightarrow 0$ , as  $|x| \longrightarrow \infty$ .

**Remark 2.2.** Since  $\gamma \ge 1$ , by Lemma 2.1, we have  $-\operatorname{div}(|\nabla v|^{p-2}\nabla v) \ge b(x)\widehat{g}(v)$ ,

Consider the following problem

$$\begin{cases} -\mathsf{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), \\ u > 0, x \in \Omega, \\ u|_{\partial\Omega} = 0, \end{cases}$$
(14)

where  $\Omega$  is a smooth bounded domain. Next, we show the existence of problem (14) by a sub-supersolution method. \_\_\_\_

For the convenience, we denote  $|u|_{\infty} = \max_{x \in \Omega} |u(x)|$  whenever  $u \in C(\overline{\Omega})$ 

**Lemma 2.3.** Let  $p > 2, q > p-1, p(x) \in C^{\alpha}(\overline{\Omega}), p(x) \ge 0$ , If f satisfies (f1) - (f3), g satisfies (g8), n satisfies (n1) and (n2), then problem (14) has at least one solution  $u \in C(\overline{\Omega}) \cap C^{1+\alpha}(\Omega)$ .

**Proof.** Let  $\phi_1 \in C(\overline{\Omega}) \cap C^{1+\alpha}(\Omega)$  be the first eigenfunction corresponding to the first eigenvalue  $\lambda_1$  of

$$-\mathsf{div}(|\nabla u|^{p-2}\nabla u) = \lambda |u|^{p-2}u, \ u > 0, \ x \in \Omega; \ u = 0, \ x \in \partial\Omega,$$
(15)

Let  $\beta = \frac{q}{q-p+1}$ , It follows by (n2) that there exists a positive constant  $\delta_1 \in (0, \min\{1, s_0\})$  such that

$$\frac{n(s)}{s^{p-1}} \ge \frac{\lambda_1 \beta^{p-1} + |p(x)|_{\infty} \beta^q |\nabla \phi_1|_{\infty}^q}{\min_{x \in \overline{\Omega}} a(x)}, \quad \forall s \in (0, \delta_1),$$

Here a(x) is the function in the condition (f3). Let  $\underline{u} = m\phi_1^\beta$  with  $m \in (0, \min\{1, \frac{\delta_1}{|\phi_1|_{\infty}^\beta}\})$ . Since  $m^{q-(p-1)} < 1$ , we see that

$$\begin{aligned} -\mathsf{div}(|\nabla \underline{u}|^{p-2}\nabla \underline{u}) + p(x)|\nabla \underline{u}|^{q} &= -\mathsf{div}(\beta^{p-1}m^{p-1}|\phi_{1}^{\beta-1}\nabla\phi_{1}|^{p-2}\phi_{1}^{\beta-1}\nabla\phi_{1}) \\ &+ p(x)\beta^{q}m^{q}\phi_{1}^{(\beta-1)q}|\nabla\phi_{1}|^{q} \\ &= -\beta^{p-1}m^{p-1}\phi_{1}^{(\beta-1)(p-1)}\mathsf{div}(|\nabla\phi_{1}|^{p-2}\nabla\phi_{1}) \\ &- \beta^{p-1}m^{p-1}(\beta-1)(p-1)|\nabla\phi_{1}|^{p}\phi_{1}^{(\beta-1)(p-1)-1} \\ &+ p(x)\beta^{q}m^{q}\phi_{1}^{(\beta-1)q}|\nabla\phi_{1}|^{q} \\ &\leq \lambda_{1}\beta^{p-1}m^{p-1}\phi_{1}^{(p-1)\beta} + p(x)\beta^{q}m^{q}\phi_{1}^{(\beta-1)q}|\nabla\phi_{1}|^{q} \\ &\leq \min_{x\in\overline{\Omega}}a(x)n(m\phi_{1}^{\beta}) \\ &= a(x)n(\underline{u}) \\ &\leq f(x,\underline{u}), \quad x\in\Omega \end{aligned}$$

i.e.,  $\underline{u} = m\phi_1^{\beta}$  is a subsolution to problem (14). Since  $(m\phi_1^{\beta})^{p-1} \leq 1$  and  $\forall t > 0, \hat{g}(t) \geq \frac{g(t)}{t^{p-1}}$ , combining with (f2), we get

$$-\operatorname{div}(|\nabla \underline{u}|^{p-2}\nabla \underline{u}) \le b(x)g(\underline{u}) \le b(x)\underline{u}^{p-1}\widehat{g}(\underline{u}) \le b(x)\widehat{g}(\underline{u}),\tag{16}$$

On the other hand, we construct a super-solution denoted by  $\overline{u} := \Psi(\gamma w_{\Omega})$ , where  $\gamma$  and  $\Psi$  are defined as in Lemma 2.1, and  $w_{\Omega}$  is the solution of the following problem

$$-\mathsf{div}(|\nabla u|^{p-2}\nabla u) = b(x), \quad u > 0, x \in \Omega, u|_{\partial\Omega} = 0,$$

Therefore, proceed as in the proof of Lemma 2.1, we have

By (f2),

$$-\mathsf{div}(|\nabla \overline{u}|^{p-2}\nabla \overline{u}) \ge b(x)g(\overline{u}), \ x \in \Omega,$$

$$-{\rm div}(|\nabla\overline{u}|^{p-2}\nabla\overline{u})\geq f(x,\overline{u}), \ x\in\Omega,$$

i.e,  $\overline{u} = \Psi(\gamma w_{\Omega})$  is a super-solution to problem (14). By Remark 2.2, we obtain that

$$-\mathsf{div}(|\nabla \overline{u}|^{p-2}\nabla \overline{u}) \ge b(x)\widehat{g}(\overline{u}), \quad x \in \Omega,$$
(17)

Since  $\widehat{g}$  is non-increasing by the comparison principle argument, we can obtain (16) and (17) that  $\underline{u}(\underline{x}) \leq \overline{u}(\underline{x}), \ x \in \Omega$ . It follows by (Yang, 2006) that problem (14) has at least one solution  $u \in C(\overline{\Omega}) \cap C^{1+\alpha}(\Omega)$  in the ordered interval  $[\underline{u}, \overline{u}]$ .

The proof of Lemma 2.3 is finished.

**Remark 2.4.** By a simple comparison argument, we have that  $w_{\Omega} \leq w$ . Here, the function w is defined in condition (b2), and  $w_{\Omega}$  is in Lemma 2.3. Therefore,  $v_{\Omega} \leq v$ , where v is as Lemma 2.1.

#### 3 Proof of Theorem 1.

Consider the perturbed problem

$$-\mathsf{div}(|\nabla u_k|^{p-2}\nabla u_k) + p(x)|\nabla u_k|^q = f(x, u_k), u_k > 0, x \in B(0, k), u_k = 0, x \in \partial B(0, k),$$
(18)

where  $B(0,k) = \{x \in \mathbb{R}^N : |x| < k\}, k = 1, 2, 3, \cdots$ . It follows by Lemma 2.3 that problem (18) has one solution  $u_k \in C^{1+\alpha}(B(0,k)) \cap C(\overline{B}(0,k))$ . Put

$$u_k(x) = 0, \quad \forall |x| > k.$$

Let v be as in Lemma 2.1, we assert that

$$u_k(x) \le v(x), \quad x \in \mathbb{R}^N, k = 1, 2, 3 \cdots.$$
(19)

Now, we need to estimate  $\{u_k\}$ . For any bonded  $C^{2+\alpha}$ -smooth domain $\Omega' \subset \mathbb{R}^N$ , take  $\Omega_1$  and  $\Omega_2$  with  $C^{2+\alpha}$ -smooth boundaries, and  $K_1$  large enough, such that

$$\Omega' \subset \subset \Omega_1 \subset \subset \Omega_2 \subset \subset B_k, \quad k \ge K_1.$$

Note that

$$v(x) \ge u_k(x) \ge \underline{u}(x) > 0, \quad \forall \ x \in B(0, K_1),$$

$$(20)$$

when  $B(0, K_1)$  is the substitution for  $\Omega$  in the proof of Lemma 2.3. Let

$$\rho_k(x) = f(x, u_k(x)) - p(x) |\nabla u_k(x)|^q, x \in B(0, K_1),$$

For  $k \in N$  We consider the problem

$$-\mathsf{div}(|\nabla u_k|^{p-2}\nabla u_k) = \rho_k(x), \quad x \in \Omega', \quad u_k = \underline{u}, \quad x \in \partial \Omega', \tag{21}$$

Since  $\underline{u}$  is a sub-solution and v is a super-solution, the above problem has at least a solution  $\underline{u}(x) \leq u_k(x) \leq v(x)$ . This in particular gives local bounds for the sequence  $\{u_k\}$  which in turn leads to local bounds in  $C^{1+\alpha}$ . Thus for every  $m \in N$ , we can select a sequence  $\{u_k^m\}$  which converges in  $C^{1+\alpha}(\overline{\Omega'})$ . A diagonal procedure gives a subsequence (denoted again by  $u_k$ ) which converges to a function u in  $C^1(\overline{\Omega'})$ , and u satisfies

$$-\mathsf{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), \ x \in \overline{\Omega'},$$

By (20), we obtain that

$$u > 0, x \in \overline{\Omega'}$$

and we can obtain that  $u \in C^{1+\alpha}(\overline{\Omega'})$ . Since  $\Omega'$  is arbitrary, we also see that  $u \in C^{1+\alpha}_{loc}(\mathbb{R}^N)$ . It follows by (19) that

$$\lim_{|x| \to \infty} u(x) = 0$$

The proof is finished.

#### 4 The case l > 0

Next, we will consider the following problem

$$\begin{cases} -\mathsf{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), \\ u > l > 0, x \in \mathbb{R}^N, \\ \lim_{|x| \to \infty} u(x) = l, \end{cases}$$
(22)

**Theorem 2.** Let q > p-1,  $p(x) \in C^{\alpha}_{loc}(\mathbb{R}^N)$  be non-negative . If f satisfies (f1) - (f3), g satisfies (g8), n satisfies (n1),  $(n2) \lim_{s \longrightarrow 0^+} \frac{n(s)}{s^{p-1}} = \infty$ , and (n3) n(x) is increasing on  $(0,\infty)$ , then problem (22) has at least one solution  $u \in C^{1+\alpha}(\mathbb{R}^N)$ .

**Lemma 2.5.** If *b* satisfy (*b*1) and (*b*2), and *g* satisfies (*g*8), then there exists a function  $v := \Phi(\beta w(x)) + l \in C^1_{loc}(\mathbb{R}^N)$  such that

$$-\operatorname{div}(|\nabla v|^{p-2}\nabla v) \ge b(x)g(v(x)), \quad v(x) > l, x \in \mathbb{R}^N, \lim_{|x| \to \infty} v(x) = l,$$
(23)

for large  $\beta \ge 1$ , where w is the solution of problem (3).

**Proof.** Since g satisfies (g8), we define

$$\widehat{g}(t) := \sup\{\frac{g(s)}{s^{p-1}} : s > t\}, \qquad t > 0.$$

we denote that  $\widehat{g}$  is non-increasing, positive and  $\widehat{g}(t) \geq \frac{g(t)}{t^{p-1}}$ . Furthermore, by (g8) we have  $\widehat{g}(t) < |w|_{\infty}^{1-p}$  for sufficiently large t.

Let

$$h(t) := \frac{2}{t} \int_{\frac{t}{2}}^{t} \widehat{g}(s) ds, \qquad t > 0.$$
(24)

It is shown in (Ladyzenskaja and Ural'tseva, 1968) that h is  $C^1$ , non-increasing and  $\hat{g}(t) \le h(t) \le \hat{g}(\frac{t}{2})$  for all  $t \in (0, \infty)$ .

Since h is non-increasing, we note that  $h(t) \to \alpha < |w|_{\infty}^{1-p}$  at  $t \to \infty$  for some  $\alpha \in [0, \infty)$ . Now, let we set  $\Phi(t)$  satisfies

$$\int_{0}^{\Phi(t)} \frac{s}{h^{\frac{1}{p-1}}(s+l)(s+l)} ds = t.$$

By direct calculation, we see that

$$\Phi'(t) = \frac{h^{\frac{1}{p-1}}(\Phi(t)+l)(\Phi(t)+l)}{\Phi(t)},$$

and  $\Phi(t) > 0$ , for t > 0,  $\Phi(0) = 0$ . Let we set  $v(x) := \Phi(\beta w(x)) + l$ , where  $\beta$  large enough and satisfies  $\beta \ge v(x) - l$ . A simple computation shows that v has the desired properties.

Indeed, on recalling  $-\operatorname{div}(|\nabla w|^{p-2}\nabla w) = b(x)$ , we see that

$$\begin{aligned} -\operatorname{div}(|\nabla v|^{p-2}\nabla v) &= -\operatorname{div}(|\frac{v}{v-l}h^{\frac{1}{p-1}}(v)\beta\nabla w|^{p-2}\frac{v}{v-l}h^{\frac{1}{p-1}}(v)\beta\nabla w) \\ &= -\operatorname{div}((\frac{v}{v-l})^{p-1}h(v)\beta^{p-1}|\nabla w|^{p-2}\nabla w) \\ &= -\beta^{p-1}(\frac{v}{v-l})^{p-1}h(v)\operatorname{div}(|\nabla w|^{p-2}\nabla w) \\ &- \beta^{p}|\nabla w|^{p}\frac{d[(\frac{v}{v-l})^{p-1}h(v)]}{dv}h^{\frac{1}{p-1}}(v)\frac{v}{v-l} \\ &= -\beta^{p-1}\frac{v^{p-1}}{(v-l)^{p-1}}h(v)\operatorname{div}(|\nabla w|^{p-2}\nabla w) \\ &- (p-1)\beta^{p}|\nabla w|^{p}h^{\frac{1}{p-1}}(v)(1+\frac{l}{v-l})^{p-1}\frac{-l}{(v-l)^{2}}h(v) \\ &- \beta^{p}|\nabla w|^{p}h^{\frac{1}{p-1}}(v)(1+\frac{l}{v-l})^{p}h'(v) \\ &\geq -\beta^{p-1}\frac{v^{p-1}}{(v-l)^{p-1}}h(v)\operatorname{div}(|\nabla w|^{p-2}\nabla w) \\ &= b(x)\beta^{p-1}\frac{v^{p-1}}{(v-l)^{p-1}}h(v) \\ &\geq b(x)(v-l)^{p-1}\frac{v^{p-1}}{(v-l)^{p-1}}\frac{g(v)}{v^{p-1}} \\ &= b(x)g(v) \quad x \in \mathbb{R}^{N}, \end{aligned}$$

Moreover, since  $\Phi(0) = 0$ , it is clear that  $v(x) \to l$ , as  $|x| \to \infty$ .

**Proof of Theorem 2** Consider the perturbed problem

$$-\mathsf{div}(|\nabla u_k|^{p-2}\nabla u_k) + p(x)|\nabla u_k|^q = f(x, u_k), u_k > l > 0, x \in B(0, k), u_k = l, x \in \partial B(0, k), \quad (25)$$

where  $B(0,k) = \{x \in \mathbb{R}^N : |x| < k\}$ ,  $k = 1, 2, 3, \cdots$ . Let  $U_k(x) = u_k(x) - l$ , where  $U_k(x)$  is the solution of (18). Then, it follows by Lemma 2.3 that problem (18) has one solution  $U_k \in C^{1+\alpha}(B(0,k)) \cap C(\overline{B}(0,k))$ , thus, problem (25) has one solution  $u_k \in C^{1+\alpha}(B(0,k)) \cap C(\overline{B}(0,k))$ . Put

$$u_k(x) = l, \quad \forall |x| > k.$$

Let v be as in Lemma 2.5, we assert that

$$u_k(x) \le v(x), \quad x \in \mathbb{R}^N, k = 1, 2, 3 \cdots.$$
 (26)

Indeed,

$$-\mathsf{div}(|\nabla v|^{p-2}\nabla v) \ge b(x)g(v(x)) \ge f(x,v) - p(x)|\nabla v|^q,$$

By the comparison principle argument, we can obtain (26).

Now, we need to estimate  $\{u_k\}$ . For any bonded  $C^{2+\alpha}$ -smooth domain  $\Omega' \subset \mathbb{R}^N$ , take  $\Omega_1$  and  $\Omega_2$  with  $C^{2+\alpha}$ -smooth boundaries, and  $K_1$  large enough, such that

$$\Omega^{'} \subset \subset \Omega_1 \subset \subset \Omega_2 \subset \subset B_k, \quad k \ge K_1,$$

Note that

$$v(x) \ge u_k(x) \ge \underline{U}(x) > l, \quad \forall \ x \in B(0, K_1), \tag{27}$$

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where  $\underline{U}(x) = \underline{u}(x) + l$ , and  $\underline{u}(x)$  is defined by Lemma 2.3. When  $B(0, K_1)$  is the substitution for  $\Omega$  in the proof of Lemma 2.3, by (n3) it is easy to see that  $\underline{U}(x)$  is the sub-solution of (25). Let

$$\rho_k(x) = f(x, u_k(x)) - p(x) |\nabla u_k(x)|^q, x \in \overline{B}(0, K_1),$$

For  $k \in N$  We consider the problem

$$-\operatorname{div}(|\nabla u_k|^{p-2}\nabla u_k) = \rho_k(x), \quad x \in \Omega', \quad u_k = \underline{U}, \quad x \in \partial \Omega', \quad (28)$$

Since  $\underline{U}$  is a sub-solution and v is a super-solution, the above problem has at least a solution  $\underline{U}(x) \leq u_k(x) \leq v(x)$ . This in particular gives local bounds for the sequence  $\{u_k\}$  which in turn leads to local bounds in  $C^{1+\alpha}$ . Thus for every  $m \in N$ , we can select a sequence  $\{u_k^m\}$  which converges in  $C^{1+\alpha}(\overline{\Omega'})$ . A diagonal procedure gives a subsequence (denoted again by  $u_k$ ) which converges to a function u in  $C^1(\overline{\Omega'})$ , and u satisfies

$$-\mathrm{div}(|\nabla u|^{p-2}\nabla u) + p(x)|\nabla u|^q = f(x,u), \ x \in \overline{\Omega'},$$

By (27), we obtain that

$$u > l, x \in \overline{\Omega'}$$

and we can obtain that  $u \in C^{1+\alpha}(\overline{\Omega'})$ . Since  $\Omega'$  is arbitrary, we also see that  $u \in C^{1+\alpha}_{loc}(\mathbb{R}^N)$ . It follows by (26) that

$$\lim_{|x| \to \infty} u(x) = l$$

The proof is finished.

#### 5 Conclusions

The boundary value quasilinear differential equation systems (1) and (22) are mathematical models occurring in the studies of the p-Laplace equation, generalized reaction-diffusion theory, non-Newtonian fluid theory, and the turbulent flow of a gas in porous medium. In the non-Newtonian fluid theory, the quantity p is characteristic of the medium. Media with p > 2 are called dilatant fluids and those with p < 2 are called pseudoplastics. If p = 2, they are Newtonain fluids. When p=/ 2, the problem becomes more complicated since certain nice properties in herent to the case m = 2 seem to be lost or at least difficult to verify. The main differences between m = 2 and m =/ 2 can be founded in (Guo, 1992; Guo and Webb, 1994). When p = 2, it is well known that all the positive solutions in C2(BR) of the problem

4u + f(u) = 0 in BR;

u(x) = 0 on @BR;

are radially symmetric solutions for very general f (see Gidas and Nirenberg, 1979). Unfortunately, this result does not apply to the case p = / 2. Kichenassary and Smoller showed that there exist many positive nonradial solutions of the above problem for some f (see Kichenassamy and Smoller, 1990). The major stumbling block in the case of p = /2 is that certain nice features inherent to the case p = 2 seem to be lost or at least difficult to verify. In this paper, we first provide a suitable supersolution for problem (1) and show the existence of positive solutions in bounded domain. Then, we prove Theorem 1, moreover, we have studied the case l > 0.

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